

VIABILITY FOR MULTI-VALUED SEMILINEAR REACTION-DIFFUSION SYSTEMS*

Monica Burlică[†]

Abstract

The aim of this paper is to prove some viability results for semilinear reaction-diffusion systems governed by multi-valued continuous perturbations of infinitesimal generators of C_0 -semigroups.

MSC: Primary 47J35, 35K57, 35K45; Secondary 47D03, 47D60.

keywords: C_0 -semigroup, reaction-diffusion system, viability, tangency set, tangency condition.

1 Introduction

The purpose of this paper is to prove some viability results referring to a class of semilinear reaction-diffusion systems, results announced without proofs in Burlică [1]. Let $(X, \|\cdot\|_X)$ and $(Y, \|\cdot\|_Y)$ be real Banach spaces, $A : D(A) \subseteq X \rightarrow X$ and $B : D(B) \subseteq Y \rightarrow Y$ the infinitesimal generators of two C_0 -semigroups, $\{S_A(t) : X \rightarrow X; t \geq 0\}$ and $\{S_B(t) : Y \rightarrow Y; t \geq 0\}$ respectively, \mathcal{K} a nonempty and locally closed subset in $X \times Y$, $F : \mathcal{K} \rightarrow X$ a

*Accepted for publication on 12.01.2010.

[†]monicaburlica@yahoo.com Department of Matematics Graduate School, "Al.I.Cuza" University Iași, România; This work was supported by the PN-II-ID-PCE-2007-1, Grant ID-397.

given function and $G : \mathcal{K} \rightsquigarrow Y$ a given multi-function. We consider a semi-multi-valued reaction-diffusion system of the form:

$$\begin{cases} u'(t) = Au(t) + F(u(t), v(t)), & t \geq 0 \\ v'(t) \in Bv(t) + G(u(t), v(t)), & t \geq 0 \\ u(0) = \xi, \quad v(0) = \eta, \end{cases} \quad (1)$$

where $\xi \in X$, $\eta \in Y$.

Definition 1. *By a mild solution of the multi-valued Cauchy problem (1) on $[0, T]$ we mean a continuous function $(u, v) : [0, T] \rightarrow \mathcal{K}$, for which there exists $g \in L^1(0, T; Y)$ such that $g(s) \in G(u(s), v(s))$ a.e. for $s \in [0, T]$ and*

$$\begin{cases} u(t) = S_A(t)\xi + \int_0^t S_A(t-s)F(u(s), v(s)) ds \\ v(t) = S_B(t)\eta + \int_0^t S_B(t-s)g(s) ds \end{cases} \quad (2)$$

for each $t \in [0, T]$.

Definition 2. *The set \mathcal{K} is viable with respect to $(A + F, B + G)$ if for each $(\xi, \eta) \in \mathcal{K}$ there exists $T > 0$ such that the Cauchy problem (1) has at least one mild solution $(u, v) : [0, T] \rightarrow \mathcal{K}$.*

2 Preliminaries

We assume that the reader is familiar with the basic concepts and results concerning multi-functions, linear evolution and semilinear differential inclusions in Banach spaces and we refer to Cârjă [4] and Vrabie [9] for details.

In the sequel $(X, \|\cdot\|)$ will always be a Banach space. For $\xi \in X$ and $\rho > 0$, $D(\xi, \rho)$ denotes the closed ball in X of radius ρ centered in ξ and $\text{dist}(E, K)$ denotes the usual distance between the subsets E and K , i.e. $\text{dist}(E, K) = \inf_{(x,y) \in E \times K} \|x - y\|$.

We begin by recalling some definitions and basic results concerning u.s.c. multi-functions, the Hausdorff measure of noncompactness and uniqueness functions.

Let K be a subset in X and $F : K \rightsquigarrow X$ a given multi-function, i.e a function $F : K \rightarrow 2^X$.

Definition 3. *The multi-function $F : K \rightsquigarrow X$ is upper semicontinuous (u.s.c.) at $\xi \in K$ if for every open neighborhood V of $F(\xi)$ there exists an open neighborhood U of ξ such that $F(\eta) \subseteq V$ for each $\eta \in U \cap K$. We say that multi-function $F : K \rightsquigarrow X$ is upper semicontinuous (u.s.c.) on K if it is u.s.c. at each $\xi \in K$.*

In all that follows, strongly-weakly u.s.c. designates a multi-function which is u.s.c. if its domain is endowed with the strong (norm) topology and its range is endowed with the weak topology.

Lemma 1. *Let X be a Banach space, K a nonempty subset in X and $F : K \rightsquigarrow X$ a nonempty and (weakly) compact valued, (strongly-weakly) u.s.c. multi-function. Then, for each compact subset C of K , $\cup_{\xi \in C} F(\xi)$ is (weakly) compact and, in particular, there exists $M > 0$ such that $\|\eta\| \leq M$ for each $\xi \in C$ and each $\eta \in F(\xi)$.*

See Cârjă-Necula-Vrabie [6], Lemma 2.6.1, p.47.

Lemma 2. *Let X be a Banach space, K a nonempty subset in X and $F : K \rightsquigarrow X$ be a nonempty, closed and convex valued, strongly-weakly u.s.c. multi-function. Let $u_m : [0, T] \rightarrow X$ and $f_m \in L^1(0, T; X)$ be such that $f_m(t) \in F(u_m(t))$ for each $m \in \mathbf{N}$ and a.e. for $t \in [0, T]$. If $\lim_m u_m(t) = u(t)$ a.e. for $t \in [0, T]$ and $\lim_m f_m = f$ weakly in $L^1(0, T; X)$, then $f(t) \in F(u(t))$ a.e. for $t \in [0, T]$.*

See Cârjă-Necula-Vrabie [6], Lemma 2.6.2, p. 47-48.

Let $\mathcal{B}(X)$ be the family of all bounded subsets of X .

Definition 4. *The function $\beta : \mathcal{B}(X) \rightarrow \mathbf{R}_+$, defined by*

$$\beta(B) = \inf \left\{ \varepsilon > 0; \exists x_1, x_2, \dots, x_{n(\varepsilon)} \in X, B \subseteq \bigcup_{i=1}^{n(\varepsilon)} D(x_i, \varepsilon) \right\}$$

is called the Hausdorff-measure of noncompactness on X .

Remark 1. *We have $\beta(B) = 0$ if and only if B is a relatively compact set. If X is finite dimensional, the class of relatively compact subsets of X coincides with $\mathcal{B}(X)$, so, in this case, $\beta \equiv 0$.*

Lemma 3. *Let Y be a subspace in X , let $B \in \mathcal{B}(X)$ and let*

$$\beta_Y(B) = \inf \left\{ \varepsilon > 0; \exists x_1, x_2, \dots, x_{n(\varepsilon)} \in Y, B \subseteq \bigcup_{i=1}^{n(\varepsilon)} D(x_i, \varepsilon) \right\}.$$

Then for each $B \in \mathcal{B}(Y)$ we have

$$\beta(B) \leq \beta_Y(B) \leq 2\beta(B).$$

For details, see Cârjă-Necula-Vrabie [6], Problem 2.7.2, p.49.

Definition 5. *A function $\omega : \mathbf{R}_+ \rightarrow \mathbf{R}_+$ which is continuous, nondecreasing and the only solution of the Cauchy problem*

$$\begin{cases} x'(t) = \omega(x(t)) \\ x(0) = 0 \end{cases}$$

is $x \equiv 0$ is called a uniqueness function.

Remark 2. *If $\omega : \mathbf{R}_+ \rightarrow \mathbf{R}_+$ is a uniqueness function, then, for each $k > 0$, $k\omega$ is a uniqueness function too.*

Next, we recall for easy reference the basic viability results, established in Cârjă-Necula-Vrabie [5] and [6], concerning the autonomous multi-valued semilinear Cauchy problem

$$\begin{cases} u'(t) \in Au(t) + F(u(t)), & t \geq 0 \\ u(0) = \xi, \end{cases} \quad (3)$$

where $A : D(A) \subseteq X \rightarrow X$ is the infinitesimal generator of C_0 -semigroup $\{S(t) : X \rightarrow X; t \geq 0\}$, K is a nonempty subset in X and $F : K \rightsquigarrow X$ is a given multi-function.

Definition 6. *By a mild solution of the problem (3) on $[0, T]$ we mean a continuous function $u : [0, T] \rightarrow K$, for which there exists $f \in L^1(0, T; X)$ such that $f(s) \in F(u(s))$ a.e. for $s \in [0, T]$ and*

$$u(t) = S(t)\xi + \int_0^t S(t-s)f(s) ds \quad (4)$$

for each $t \in [0, T]$.

Definition 7. *The set $K \subseteq X$ is viable with respect to $A + F$ if for each $\xi \in K$, there exists $T > 0$ such that the Cauchy problem (3) has at least one mild solution $u : [0, T] \rightarrow K$.*

In Cârjă-Necula-Vrabie [5] and [6] a new concept of tangent set is defined and used in order to prove necessary and sufficient conditions for viability with respect to $A + F$. We recall that the subset $K \subseteq X$ is locally closed if for each $\xi \in K$ there exists $\rho > 0$ such that $D(\xi, \rho) \cap K$ is closed. Each subset in X which is either open or closed is locally closed. Moreover, each subset K in X which is closed relative to some open subset D , i.e. for which there exists a closed subset $C \subset X$ such that $K = C \cap D$, is locally closed in X .

If E is a nonempty subset in X , we denote by

$$\mathcal{E} = \{f \in L^1(\mathbf{R}_+; X); f(s) \in E \text{ a.e. for } s \in \mathbf{R}_+\}.$$

Definition 8. *Let $A : D(A) \subseteq X \rightarrow X$ be the infinitesimal generator of a C_0 -semigroup, $\{S(t) : X \rightarrow X; t \geq 0\}$, K a subset in X and $\xi \in K$. We say that the set $E \subseteq X$ is A -quasi-tangent to the set K at the point ξ if for each $\rho > 0$, we have*

$$\liminf_{h \downarrow 0} \frac{1}{h} \text{dist}(\mathcal{S}_{\mathcal{E}}(h)\xi; K \cap D(\xi, \rho)) = 0, \quad (5)$$

where

$$\mathcal{S}_{\mathcal{E}}(h)\xi = \left\{ S(h)\xi + \int_0^h S(h-s)f(s) ds; f \in \mathcal{E} \right\}.$$

We denote by $\mathcal{QTS}_K^A(\xi)$ the class of all A -quasi-tangent sets to K at $\xi \in K$.

Remark 3. *Let $K \subseteq X, \xi \in K$ and $E \subseteq X$. Then the following conditions are equivalent:*

- (i) $E \in \mathcal{QTS}_K^A(\xi)$;
- (ii) for each $\varepsilon > 0$, $\rho > 0$ and $\delta > 0$ there exist $h \in (0, \delta)$, $p \in D(0, \varepsilon)$ and $f \in \mathcal{E}$ such that

$$S(h)\xi + \int_0^h S(h-s)f(s) ds + hp \in K \cap D(\xi, \rho);$$

(iii) there exist three sequences, $(h_n)_n$ in \mathbf{R}_+ with $h_n \downarrow 0$, $(p_n)_n$ in X with $\lim_n p_n = 0$, and $(f_n)_n \in \mathcal{E}$, with $\lim_n \int_0^{h_n} S(h_n - s)f_n(s) ds = 0$ and

$$S(h_n)\xi + \int_0^{h_n} S(h_n - s)f_n(s) ds + h_n p_n \in K.$$

Before proceeding to the main results in this section, we introduce first:

Definition 9. A set $C \subseteq X$ is quasi-weakly (relatively) compact if, for each $r > 0$, $C \cap D(0, r)$ is weakly (relatively) compact.

We present now a necessary condition for mild viability.

Theorem 1. Let X be a Banach space, $A : D(A) \subseteq X \rightarrow X$ the infinitesimal generator of a C_0 -semigroup, $\{S(t) : X \rightarrow X; t \geq 0\}$, K a nonempty subset in X and $F : K \rightsquigarrow X$ a nonempty valued multi-function. If K is viable with respect to $A + F$ then, for each $\xi \in K$ at which F is u.s.c. and $F(\xi)$ is convex and quasi-weakly compact, we have

$$F(\xi) \in \mathcal{QTS}_K^A(\xi). \quad (6)$$

The main sufficient condition for mild viability is:

Theorem 2. Let X be a Banach space, $A : D(A) \subseteq X \rightarrow X$ the infinitesimal generator of a compact C_0 -semigroup, $\{S(t) : X \rightarrow X; t \geq 0\}$, K a nonempty and locally closed subset in X and $F : K \rightsquigarrow X$ a nonempty, weakly compact and convex valued, strongly-weakly u.s.c. multi-function. If for each $\xi \in K$, the tangency condition (6) is satisfied, then K is viable with respect to $A + F$.

3 The main results

We focus our attention to the main necessary and sufficient conditions for viability in the case of reaction diffusion systems of the form (1).

Let $(X, \|\cdot\|_X)$ and $(Y, \|\cdot\|_Y)$ two real Banach spaces, $\mathcal{K} \subseteq X \times Y$, $F : \mathcal{K} \rightarrow X$, $G : \mathcal{K} \rightsquigarrow Y$, and $\xi \in X$, $\eta \in Y$. We assume that the operators $A : D(A) \subseteq X \rightarrow X$ and $B : D(B) \subseteq Y \rightarrow Y$ are the generators of two C_0 -semigroups, $\{S_A(t) : X \rightarrow X; t \geq 0\}$ and $\{S_B(t) : Y \rightarrow Y; t \geq 0\}$ respectively.

The system (1) can be written as a multi-valued semilinear Cauchy problem in a product space. Let $\mathcal{X} = X \times Y$ be endowed with the norm $\|\cdot\|$, defined by $\|(x, y)\|_{\mathcal{X}} = \|x\|_X + \|y\|_Y$, for each $(x, y) \in \mathcal{X}$. Let $\mathcal{A} = (A, B) : D(\mathcal{A}) \subseteq \mathcal{X} \rightarrow \mathcal{X}$ be defined by $D(\mathcal{A}) = D(A) \times D(B)$, $\mathcal{A}(x, y) = (Ax, By)$ for each $(x, y) \in D(\mathcal{A})$ and let $\mathcal{F} : \mathcal{K} \rightsquigarrow \mathcal{X}$, $\mathcal{F}(z) = (F(z), G(z))$ for each $z = (x, y) \in \mathcal{K}$, where $(F(z), G(z)) = \{F(z), \eta\}$; $\eta \in G(z)\}$. So, the system (1) can be written as

$$\begin{cases} z'(t) \in \mathcal{A}z(t) + \mathcal{F}(z(t)) \\ z(0) = \zeta, \end{cases} \quad (7)$$

where $\zeta = (\xi, \eta)$. We notice that, in the hypotheses above, \mathcal{A} is the infinitesimal generator of a C_0 -semigroup $\{S(t) : \mathcal{X} \rightarrow \mathcal{X}; t \geq 0\}$, given by

$$S(t)(\xi, \eta) = (S_A(t)\xi, S_B(t)\eta)$$

for each $t \geq 0$ and $(\xi, \eta) \in \mathcal{X}$. Let us remark that \mathcal{K} is viable with respect to $(A + F, B + G)$ in sense of Definition 2 if and only if \mathcal{K} is viable with respect to $\mathcal{A} + \mathcal{F}$ in sense of Definition 7, which means that for each $\zeta \in \mathcal{K}$, there exists $T > 0$ such that the problem (7) has at least one mild solution $z : [0, T] \rightarrow \mathcal{K}$.

From Theorem 1 we deduce the necessary condition for viability.

Theorem 3. *Let X and Y be Banach spaces, \mathcal{K} a nonempty subset in $X \times Y$, $A : D(A) \subseteq X \rightarrow X$, $B : D(B) \subseteq Y \rightarrow Y$ the infinitesimal generators of two C_0 -semigroups, $\{S_A(t) : X \rightarrow X; t \geq 0\}$ and $\{S_B(t) : Y \rightarrow Y; t \geq 0\}$ respectively, $F : \mathcal{K} \rightarrow X$ a continuous function and $G : \mathcal{K} \rightsquigarrow Y$ a nonempty, convex and quasi-weakly compact valued, u.s.c. multi-function. If \mathcal{K} is viable with respect to $(A + F, B + G)$ then, for each $\zeta \in \mathcal{K}$ we have:*

$$(F(\zeta), G(\zeta)) \in \mathcal{QTS}_{\mathcal{K}}^A(\zeta). \quad (8)$$

In order to state and prove some sufficient conditions for viability, we need the hypotheses below.

(H₁) $A : D(A) \subseteq X \rightarrow X$, $B : D(B) \subseteq Y \rightarrow Y$ are the generators of two C_0 -semigroups, $\{S_A(t) : X \rightarrow X; t \geq 0\}$ and $\{S_B(t) : Y \rightarrow Y; t \geq 0\}$ respectively;

(H₂) $\mathcal{K} \subseteq X \times Y$ is nonempty and locally closed;

(H₃) $F : X \times Y \rightarrow X$ is continuous and globally Lipschitz with respect to its first argument, i.e. there exists $L > 0$ such that

$$\|F(u, v) - F(\tilde{u}, v)\| \leq L\|u - \tilde{u}\|$$

for each $(u, v), (\tilde{u}, v) \in X \times Y$;

(H₄) $A + F$ is Y -uniformly locally of β_X -compact type, which means that F is continuous and, for each $\zeta = (\xi, \eta) \in \mathcal{K}$, there exist $\rho > 0$, a continuous function $l : \mathbf{R}_+ \rightarrow \mathbf{R}_+$ and a uniqueness function $\omega : \mathbf{R}_+ \rightarrow \mathbf{R}_+$ such that, for each subset $C \subseteq D_{X \times Y}(\zeta, \rho) \cap \mathcal{K}$, with $\Pi_Y C$ relatively compact, and for each $t > 0$, we have

$$\beta_X(S_A(t)F(C)) \leq l(t)\omega(\beta_{X \times Y}(C));$$

(H₅) $\{S_B(t) : Y \rightarrow Y, t \geq 0\}$ is compact;

(H₆) $G : \mathcal{K} \rightsquigarrow Y$ is strongly-weakly u.s.c. multi-function with nonempty, convex and weakly compact values.

Theorem 4. *Assume that (H₁), (H₂), (H₃), (H₅) and (H₆) are satisfied. If, for each $\zeta \in \mathcal{K}$ the tangency condition (8) is satisfied, then \mathcal{K} is viable with respect to $(A + F, B + G)$.*

Theorem 5. *Assume that (H₁), (H₂), (H₄), (H₅) and (H₆) are satisfied. If, for each $\zeta \in \mathcal{K}$ the tangency condition (8) is satisfied, then \mathcal{K} is viable with respect to $(A + F, B + G)$.*

A nonautonomous variant of Theorem 4 is stated below. Let us consider the quasi-autonomous semilinear system

$$\begin{cases} u'(t) = Au(t) + F(t, u(t), v(t)), & t \geq \tau \\ v'(t) \in Bv(t) + G(t, u(t), v(t)), & t \geq \tau \\ u(\tau) = \xi, \quad v(\tau) = \eta \end{cases} \quad (9)$$

where $\mathcal{K} \subseteq \mathbf{R} \times X \times Y$, $F : \mathbf{R} \times X \times Y \rightarrow X$ and $G : \mathcal{K} \rightsquigarrow Y$.

Let $\mathcal{X} = \mathbf{R} \times X$ endowed with the norm $\|(t, x)\|_{\mathcal{X}} = |t| + \|x\|_X$, for each $(t, x) \in \mathcal{X}$. Let $\mathcal{A} = (0, A)$, $z(s) = (s + \tau, u(s + \tau))$, $w(s) = v(s + \tau)$ and let $\mathcal{F} : \mathcal{X} \times Y \rightarrow X$, $\mathcal{F}(z, w) = (1, F(z, w))$ for each $(z, w) \in \mathcal{X} \times Y$. With the

notation above the system (9) can be written as an autonomous one in the space $\mathcal{X} \times Y$

$$\begin{cases} z'(s) = \mathcal{A}z(s) + \mathcal{F}(z(s), w(s)), & s \geq 0 \\ w'(s) \in B(s) + G(z(s), w(s)), & s \geq 0 \\ z(0) = (\tau, \xi), \quad w(0) = \eta \end{cases} \quad (10)$$

From Theorem 4 we deduce:

Theorem 6. *Assume that X and Y are Banach spaces and (H_1) , (H_5) are satisfied. Let $\mathcal{K} \subseteq \mathbf{R} \times X \times Y$ be a nonempty and locally closed set, $F : \mathbf{R} \times X \times Y \rightarrow X$ be continuous and $G : \mathcal{K} \rightsquigarrow Y$ be locally bounded, strongly-weakly u.s.c. multi-function with nonempty, convex and weakly compact values. Let us assume that F is globally Lipschitz with respect to its first and second arguments i.e. there exists $L > 0$ such that*

$$\|F(t, u, v) - F(\tilde{t}, \tilde{u}, v)\| \leq L(|t - \tilde{t}| + \|u - \tilde{u}\|).$$

If, for each $(\tau, \xi, \eta) \in \mathcal{K}$ the next tangency condition

$$(1, F(\tau, \xi, \eta), G(\tau, \xi, \eta)) \in \mathcal{QTS}_{\mathcal{K}}^{(A, B)}(\tau, \xi, \eta) \quad (11)$$

is satisfied, then \mathcal{K} is viable with respect to $(A + F, B + G)$.

The nonautonomous case was studied in Necula-Vrabie [8] in the case when A and B are m -dissipative possibly nonlinear operators, while both F and G are single-valued, F is jointly continuous and locally Lipschitz with respect to its second variable, G is continuous and the semigroup generated by B is compact.

4 Proofs of Theorem 4 and Theorem 5

The proofs are essentially based on the construction of an ε -approximate solution for the Cauchy problem (3), i.e. a 5-uple $(\sigma, \theta, g, f, u)$ given by lemma below.

Lemma 4. *Let X, Y be real Banach spaces, $\mathcal{A} : D(\mathcal{A}) \subseteq X \times Y \rightarrow X \times Y$ the infinitesimal generator of a C_0 -semigroup, $\{\mathcal{S}(t) : X \times Y \rightarrow X \times Y; t \geq 0\}$, \mathcal{K} a nonempty and locally closed subset in $X \times Y$ and $\mathcal{F} : \mathcal{K} \rightsquigarrow X \times Y$ a given nonempty-valued and locally bounded multi-function satisfying the tangency condition (6). Let $\zeta \in \mathcal{K}$ be arbitrary and let $r > 0$ be such that*

$D_{X \times Y}(\zeta, r) \cap \mathcal{K}$ is closed. Then, there exist $\rho \in (0, r]$ and $T > 0$ such that, for each $\varepsilon \in (0, 1)$, there exist $\sigma : [0, T] \rightarrow [0, T]$ nondecreasing, $\theta : \{(t, s); 0 \leq s < t \leq T\} \rightarrow [0, T]$ measurable, $\mathcal{G} : [0, T] \rightarrow X \times Y$, $\tilde{f} : [0, T] \rightarrow X \times Y$ Bochner integrable and $z : [0, T] \rightarrow X \times Y$ continuous such that:

- (i) $s - \varepsilon \leq \sigma(s) \leq s$ for each $s \in [0, T]$;
- (ii) $z(\sigma(s)) \in D_{X \times Y}(\zeta, r) \cap \mathcal{K}$ for each $s \in [0, T]$ and $z(T) \in D_{X \times Y}(\zeta, r) \cap \mathcal{K}$;
- (iii) $\|\mathcal{G}(s)\| \leq \varepsilon$ for each $s \in [0, T]$ and $\tilde{f}(s) \in \mathcal{F}(z(\sigma(s)))$ a.e. for $s \in [0, T]$;
- (iv) $\theta(t, s) \leq t$ for each $0 \leq s < t \leq T$ and $t \mapsto \theta(t, s)$ is nonexpansive on $(s, T]$;
- (v) $z(t) = \mathcal{S}(t)\zeta + \int_0^t \mathcal{S}(t-s)\tilde{f}(z(s)) ds + \int_0^t \mathcal{S}(\theta(t, s))\mathcal{G}(s) ds$
for each $t \in [0, T]$;
- (vi) $\|z(t) - z(\sigma(t))\| \leq \varepsilon$ for each $t \in [0, T]$.

See Cârjă-Necula-Vrabie [5] and [6], Lemma 9.3.1, p.185.

Remark 4. Let $\mathcal{K} \subseteq X \times Y$ be a nonempty, locally closed set and $G : \mathcal{K} \rightsquigarrow Y$ be a strongly-weakly u.s.c. multi-function with nonempty, convex and weakly compact valued, then G is locally bounded.

See Remark 7.1 in Cârjă-Necula-Vrabie [7].

Proof of Theorem 4 Let $\zeta = (\xi, \eta) \in \mathcal{K}$ and $r > 0$ such that $D_{\mathcal{X}}(\zeta, r) \cap \mathcal{K}$ be closed. Let us choose $\rho \in (0, r]$, $N > 0$, $M \geq 1$ and $a \geq 0$ such that $\|F(z)\|_X \leq N$ and $\|y\|_Y \leq N$ for every $z \in D_{\mathcal{X}}(\zeta, \rho) \cap \mathcal{K}$ and every $y \in G(z)$ and $\|\mathcal{S}(t)\|_{\mathcal{L}(\mathcal{X})} \leq Me^{at}$, for every $t \geq 0$. Since $t \mapsto \mathcal{S}(t)\zeta$ is continuous in $t = 0$ and $\mathcal{S}(0)\zeta = \zeta$, we may find a sufficiently small $T > 0$ such that

$$\sup_{t \in [0, T]} \|\mathcal{S}(t)\zeta - \zeta\|_{\mathcal{X}} + TMe^{aT}(N + 1) \leq \rho$$

and all the conclusions of Lemma 4, for the Cauchy problem (7), be satisfied.

Let $(\varepsilon_n)_n \downarrow 0$ be a sequence in $(0, 1)$ and let $((\sigma_n, \theta_n, \mathcal{G}_n, \tilde{f}_n, z_n))_n$ be a sequence of $(\varepsilon_n)_n$ - approximate solutions defined on $[0, T]$ whose existence is ensured by the Lemma 4. This means that $\tilde{f}_n = (f_n, g_n)$ is Lebesgue

integrable, $f_n(s) = F(z_n(\sigma_n(s)))$ and $g_n(s) \in G(z_n(\sigma_n(s)))$ a.e. for $s \in [0, T]$, and $z_n(\sigma_n(t)) \in D_{\mathcal{X}}(\zeta, \rho) \cap \mathcal{K}$, for $n = 1, 2, \dots$ and each $t \in [0, T]$, and

$$z_n(t) = \mathcal{S}(t)\zeta + \int_0^t \mathcal{S}(t-s)\tilde{f}_n(s)ds + \int_0^t \mathcal{S}(\theta_n(t, s))\mathcal{G}_n(s)ds$$

for each $n \in \mathbf{N}$ and $t \in [0, T]$. Put $z_n = (u_n, v_n)$. So, (u_n, v_n) satisfies

$$\begin{cases} u_n(t) = S_A(t)\xi + \int_0^t S_A(t-s)F(z_n(\sigma_n(s)))ds + \int_0^t S_A(\theta_n(t, s))\mathcal{G}_n^X(s)ds \\ v_n(t) = S_B(t)\eta + \int_0^t S_B(t-s)g_n(s)ds + \int_0^t S_B(\theta_n(t, s))\mathcal{G}_n^Y(s)ds, \end{cases} \quad (12)$$

where $\mathcal{G}_n(t) = (\mathcal{G}_n^X(t), \mathcal{G}_n^Y(t))$ for each $n = 1, 2, \dots$ and $t \in [0, T]$. Since $\|g_n(s)\|_Y \leq N$ for each $n = 1, 2, \dots$ and for a.a. $s \in [0, T]$, the family $\{g_n(\cdot); n \in \mathbf{N}\}$ is uniformly integrable subset in $L^1(0, T; Y)$. Since the C_0 -semigroup $\{S_B(t) : Y \rightarrow Y; t \geq 0\}$ is compact and $\|\mathcal{G}_n^Y(s)\|_Y \leq \varepsilon_n < 1$, from Theorem 8.4.2 in Vrabie [9] it follows that $\{v_n; n = 1, 2, \dots\}$ is relatively compact in $C([0, T]; Y)$. As $\lim_n \sigma_n(t) = t$ uniformly for $t \in [0, T]$ we deduce that there exists $v \in C([0, T]; Y)$ such that, on a subsequence at least, $\lim_n v_n(t) = v(t)$ and $\lim_n v_n(\sigma_n(t)) = v(t)$ uniformly for $t \in [0, T]$.

At this point let us consider the problem:

$$\begin{cases} u'(t) = Au(t) + F(u(t), v(t)), & t \geq 0 \\ u(0) = \xi, \end{cases} \quad (13)$$

where $v \in C([0, T]; Y)$ is as above. Since A is the infinitesimal generator of a C_0 -semigroup and F is continuous on $X \times Y$ and globally Lipschitz with respect to its first argument, it follows that the problem (13) has a unique mild solution $u : [0, T] \rightarrow X$, i.e.

$$u(t) = S_A(t)\xi + \int_0^t S_A(t-s)F(u(s), v(s))ds \quad (14)$$

for each $t \in [0, T]$. We will prove next that $\lim_n u_n(t) = u(t)$ uniformly for $t \in [0, T]$. Indeed, we have

$$\|u_n(\sigma_n(t)) - u(t)\|_X \leq \|u_n(\sigma_n(t)) - u_n(t)\|_X + \|u_n(t) - u(t)\|_X. \quad (15)$$

From (12) and (14), it follows that

$$\begin{aligned} & \|u_n(t) - u(t)\|_X \leq \int_0^t \|S_A(\theta_n(t, s))\|_{L(X)} \|\mathcal{G}_n^X(s)\|_X ds \\ & + \int_0^t \|S_A(t-s)\|_X \|F(u_n(\sigma_n(s)), v_n(\sigma_n(s))) - F(u(s), v(s))\|_X ds \end{aligned}$$

for each $t \in [0, T]$. Using (iii)¹, (vi) and the Lipschitz's condition for F , from (15) we obtain

$$\begin{aligned} & \|u_n(\sigma_n(t)) - u(t)\|_X \leq M e^{aT} \varepsilon_n \\ & + M e^{aT} \int_0^t \|F(u(s), v_n(\sigma_n(s))) - F(u(s), v(s))\|_X ds \\ & + L M e^{aT} \int_0^t \|u_n(\sigma_n(s)) - u(s)\|_X ds, \end{aligned} \tag{16}$$

for each $t \in [0, T]$. On the other hand, $\varepsilon_n \downarrow 0$, $v_n(\sigma_n(s)) \rightarrow v(s)$ uniformly for $s \in [0, T]$ and F is continuous. So, for each $\varepsilon > 0$ there exists $n_0 = n_0(\varepsilon)$ such that, for each $n \in \mathbf{N}$, $n \geq n_0$ and for each $t \in [0, T]$ we have:

$$M e^{aT} \varepsilon_n + M e^{aT} \int_0^t \|F(u(s), v_n(\sigma_n(s))) - F(u(s), v(s))\|_X ds \leq \varepsilon.$$

In view of (16) and the last inequality, we deduce

$$\|u_n(\sigma_n(t)) - u(t)\|_X \leq \varepsilon + L M e^{aT} \int_0^t \|u_n(\sigma_n(s)) - u(s)\|_X ds$$

for all $n \in \mathbf{N}$, $n \geq n_0$ and $t \in [0, T]$. Gronwall's Lemma implies

$$\|u_n(\sigma_n(t)) - u(t)\|_X \leq \varepsilon e^{L M T e^{aT}}$$

for each $n \in \mathbf{N}$, $n \geq n_0$ and each $t \in [0, T]$. Therefore $\lim_n u_n(\sigma_n(t)) = u(t)$ uniformly for $t \in [0, T]$. Taking into account (i) we deduce that $\lim_n u_n(t) =$

¹Throughout this section, reference to (i)–(vi) are to the corresponding items in Lemma 4.

$u(t)$ uniformly for $t \in [0, T]$. Since $(u_n(\sigma_n(t)), v_n(\sigma_n(t))) \in D_{\mathcal{X}}(\zeta, \rho) \cap \mathcal{K}$, for $n = 1, 2, \dots$ and each $t \in [0, T]$ and $D_{\mathcal{X}}(\zeta, \rho) \cap \mathcal{K}$ is closed, it follows that $(u(t), v(t)) \in D_{\mathcal{X}}(\zeta, \rho) \cap \mathcal{K}$ for each $t \in [0, T]$.

Next, we will prove that $(g_n)_n$ is weakly convergent in $L^1(0, T; Y)$ to some function g . Indeed, since G is strongly-weakly u.s.c. with weakly compact values and since $\{(u_n(\sigma_n(s)), v_n(\sigma_n(s))); n = 1, 2, \dots, s \in [0, T]\}$ is relatively compact in $X \times Y$, from Lemma 1 and using by Theorem 1.3.2. in Cârjă-Necula-Vrabie [6], it follows that the set

$$C = \overline{\text{conv}} \bigcup_{n=1}^{\infty} \bigcup_{s \in [0, T]} G(u_n(\sigma_n(s)), v_n(\sigma_n(s)))$$

is weakly compact. Since $g_n(s) \in C$ for $n = 1, 2, \dots$ and a.e. for $s \in [0, T]$, we obtain that $\{g_n(\cdot); n = 1, 2, \dots\}$ is weakly relatively compact in $L^1(0, T; Y)$. So, on a subsequence at least, $(g_n)_n$ is weakly convergent in $L^1(0, T; Y)$ to some function g . From Lemma 2 it follows that $g(s) \in G(u(s), v(s))$ a.e. for $s \in [0, T]$.

Now, let us consider the mild solution operator $Q : L^1(0, T; Y) \rightarrow C([0, T]; Y)$, defined by

$$(Qg)(t) = S_B(t)\eta + \int_0^t S_B(t-s)g(s) ds,$$

for each $t \in [0, T]$ and for each $g \in L^1(0, T; Y)$. As the graph of Q is strongly \times strongly closed and convex, it is weakly \times strongly closed. So, we may pass to the limit in the second relation of (12) and, taking into account $\|\mathcal{G}_n^Y(s)\|_Y \leq \varepsilon_n$, we obtain

$$v(t) = S_B(t)\eta + \int_0^t S_B(t-s)g(s) ds.$$

Thus (u, v) is a mild solution of (1). The proof is complete.

We prove now, that, in the hypotheses of Theorem 5, there exists at least one sequence $(\varepsilon_n)_n$, with $\varepsilon_n \downarrow 0$ such that the ε_n -approximate mild solutions sequence $((\sigma_n, \theta_n, \mathcal{G}_n, \tilde{f}_n, z_n))_n$ has the property that $z_n = (u_n, v_n)$ is, on a subsequence at least, uniformly convergent on $[0, T]$ to some function $(u, v) : [0, T] \rightarrow \mathcal{K}$ which is the mild solution of (1).

Proof of Theorem 5 Let $\zeta = (\xi, \eta) \in \mathcal{K}$ be arbitrary and let $r > 0$, $\rho \in (0, r]$, $N > 0$, $M \geq 1$, $a \geq 0$ and $T > 0$ as in proof of Theorem 4.

Since $A + F$ is Y -uniformly locally of β_X -compact type, diminishing $\rho > 0$ and $T > 0$, if necessary, it follows that there exist a continuous function $l : \mathbf{R}_+ \rightarrow \mathbf{R}_+$ and a uniqueness function $\omega : \mathbf{R}_+ \rightarrow \mathbf{R}_+$ such that

$$\beta_X(S_A(t)F(C)) \leq l(t)\omega(\beta_X(\Pi_X C)) \quad (17)$$

for each subset $C \subseteq D_{\mathcal{X}}(\zeta, \rho) \cap \mathcal{K}$, with $\Pi_Y C$ relatively compact, and for each $t \geq 0$. Let $(\varepsilon_n)_n$ with $\varepsilon_n \downarrow 0$ be a sequence in $(0, 1)$ and let $((\sigma_n, \theta_n, \mathcal{G}_n, \tilde{f}_n, z_n))_n$ be a sequence of $(\varepsilon_n)_n$ -approximate mild solutions for (7), defined on $[0, T]$. Put $\tilde{f}_n = (f_n, g_n)$ and $z_n = (u_n, v_n)$. So $f_n(s) = F(z_n(\sigma_n(s)))$, $g_n(s) \in G(z_n(\sigma_n(s)))$ a.e. for $s \in [0, T]$, and $z_n(\sigma_n(t)) \in D_{\mathcal{X}}(\zeta, \rho) \cap \mathcal{K}$, for $n = 1, 2, \dots$ and each $t \in [0, T]$. From (v), we have

$$z_n(t) = \mathcal{S}(t)\zeta + \int_0^t \mathcal{S}(t-s)\tilde{f}_n(s)ds + \int_0^t \mathcal{S}(\theta_n(t, s))\mathcal{G}_n(s)ds, \quad (18)$$

for each $n = 1, 2, \dots$ and $t \in [0, T]$. This means that (u_n, v_n) satisfies

$$\begin{cases} u_n(t) = S_A(t)\xi + \int_0^t S_A(t-s)F(z_n(\sigma_n(s)))ds + \int_0^t S_A(\theta_n(t, s))\mathcal{G}_n^X(s)ds \\ v_n(t) = S_B(t)\eta + \int_0^t S_B(t-s)g_n(s)ds + \int_0^t S_B(\theta_n(t, s))\mathcal{G}_n^Y(s)ds, \end{cases} \quad (19)$$

where

$$\begin{cases} \mathcal{G}_n(s) = (\mathcal{G}_n^X(s), \mathcal{G}_n^Y(s)) \\ \mathcal{S}(\theta_n(t, s))\mathcal{G}_n(s) = (S_A(\theta_n(t, s))\mathcal{G}_n^X(s), S_B(\theta_n(t, s))\mathcal{G}_n^Y(s)), \end{cases}$$

for each $n \in \mathbf{N}$ and $0 \leq s < t \leq T$.

Since the family $\{g_n(\cdot); n \in \mathbf{N}\}$ and $\{\mathcal{G}_n^Y(\cdot); n \in \mathbf{N}\}$ are uniformly integrable subsets in $L^1(0, T; Y)$ and the C_0 -semigroup $\{S_B(t) : Y \rightarrow Y; t \geq 0\}$ is compact, from Theorem 8.4.2 in Vrabie [9] it follows that $\{v_n; n = 1, 2, \dots\}$ is relatively compact in $C([0, T]; Y)$. As $\lim_n \sigma_n(t) = t$ uniformly for $t \in [0, T]$ we deduce that there exists $v \in C([0, T]; Y)$ such that, on a subsequence at least, $\lim_n v_n(t) = v(t)$ and $\lim_n v_n(\sigma_n(t)) = v(t)$ uniformly for $t \in [0, T]$. We will prove that $\{u_n; n = 1, 2, \dots\}$ is relatively compact in $C([0, T]; X)$.

We consider first the case when X is a separable space.

Since $\Pi_Y\{(u_n(\sigma_n(t)), v_n(\sigma_n(t))); n \geq k\} = \{v_n(\sigma_n(t)); n \geq k\}$ is relatively compact in Y , $A + F$ is Y -uniformly locally of β_X -compact type, from (17),

we get

$$\begin{aligned} & \beta_X(\{S_A(t-s)F(u_n(\sigma_n(s)), v_n(\sigma_n(s))); n \geq k\}) \\ & \leq l(t-s)\omega(\beta_X(\{u_n(\sigma_n(s)); n \geq k\})), \end{aligned} \quad (20)$$

for each $k = 1, 2, \dots$ and $0 \leq s < t \leq T$. Since $\|\mathcal{G}_n^X(s)\|_X \leq \varepsilon_n$ for each $s \in [0, T]$ it follows that $\beta_X\left(\left\{\int_0^t S_A(\theta_n(t,s))\mathcal{G}_n^X(s)ds; n \geq k\right\}\right) = 0$. Similarly, from (vi) we have that $\{u_n(\sigma_n(s)) - u_n(s); n \geq k\}$ is relatively compact, for each $k \in \mathbf{N}$ and $s \in [0, T]$, and so $\beta(\{u_n(\sigma_n(s)) - u_n(s); n \geq k\}) = 0$.

Using these arguments, the inequality (20), Lemma 2.7.2 and Problem 2.7.1 from Cârjă-Necula-Vrabie [6], we deduce that

$$\begin{aligned} \beta_X(\{u_n(t); n \geq k\}) & \leq \beta_X\left(\left\{\int_0^t S_A(t-s)F(z_n(\sigma_n(s)))ds; n \geq k\right\}\right) \\ & \quad + \beta_X\left(\left\{\int_0^t S_A(\theta_n(t,s))\mathcal{G}_n^X(s)ds; n \geq k\right\}\right) \\ & \leq \int_0^t \beta_X(\{S_A(t-s)F(z_n(\sigma_n(s))); n \geq k\})ds \\ & \leq \int_0^t l(t-s)\omega(\beta_X(\{u_n(\sigma_n(s)); n \geq k\}))ds \\ & \leq \int_0^t l(t-s)\omega(\beta_X(\{u_n(s); n \geq k\} + \{u_n(\sigma_n(s)) - u_n(s); n \geq k\}))ds \\ & \leq \int_0^t m\omega(\beta_X(\{u_n(s); n \geq k\}) + \beta_X(\{u_n(\sigma_n(s)) - u_n(s); n \geq k\}))ds \end{aligned}$$

where $m = \sup_{t \in [0, T]} l(t)$. Hence

$$\beta_X(\{u_n(t); n \geq k\}) \leq \int_0^t m\omega(\beta_X(\{u_n(s); n \geq k\}))ds,$$

for each $k = 1, 2, \dots$ and $t \in [0, T]$.

Since $\beta_X(\{u_n(t); n \geq k\}) = \beta_X(\{u_n(t); n \geq 1\})$ and we set $x(t) = \beta_X(\{u_n(t); n \geq 1\})$, $\omega_0 = m\omega$, we deduce that

$$x(t) \leq \int_0^t \omega_0(x(s))ds,$$

for all $t \in [0, T]$.

But ω_0 is a uniqueness function, so by Lemma 1.8.2 in Cârjă-Necula-Vrabie [6], we have $x(t) = 0$, for all $t \in [0, T]$, which means that

$$\beta_X(\{u_n(t); n \geq 1\}) = 0,$$

for all $t \in [0, T]$. It follows that for each $t \in [0, T]$, $\{u_n(t); n = 1, 2, \dots\}$ is relatively compact in X . Since $(F(z_n))_n$ is bounded, it is uniformly integrable, so, by Theorem 8.4.1 in Vrabie [9], there exists $u \in C([0, T]; X)$ such that, on a subsequence at least,

$$\lim_n \left(u_n(t) - \int_0^t S_A(\theta_n(t, s)) \mathcal{G}_n^X(s) ds \right) = u(t),$$

uniformly for $t \in [0, T]$. But, by (iii),

$$\lim_n \int_0^t S_A(\theta_n(t, s)) \mathcal{G}_n^X(s) ds = 0,$$

uniformly for $t \in [0, T]$, so $\lim_n u_n(t) = u(t)$, uniformly for $t \in [0, T]$.

If X is not separable, in view of Theorem 1.1.3, p.3 and Remark 1.1.2, p.4 in Vrabie [9], there exists a separable and closed subspace Z of X such that

$$S_A(t)\xi, S_A(r)F(u_n(\sigma_n(s)), v_n(\sigma_n(s))), S_A(\theta_n(r, s))\mathcal{G}_n^X(s) \in Z$$

for $n = 1, 2, \dots$ and a.e. for $t, r, s \in [0, T]$. Using Lemma 2.1 and the monotonicity of ω , we have

$$\beta_Z(S_A(t)F(C)) \leq 2\beta_X(S_A(t)F(C)) \leq 2l(t)\omega(\beta_X(\Pi_X C)) \leq 2l(t)\omega(\beta_Z(\Pi_X C)),$$

for each $t > 0$ and for each set $C \subseteq D_{\mathcal{X}}(\zeta, \rho) \cap \mathcal{K} \cap (Z \times Y)$ with $\Pi_Y C$ relatively compact. Since the restriction of β_Z to $\mathcal{B}(Z)$ is the Hausdorff measure of noncompactness on Z , we repeat now the arguments in the separable case with β_X replaced by β_Z and ω replaced by 2ω .

So, $\lim_n u_n(t) = u(t)$, uniformly for $t \in [0, T]$. From now on the proof follows the same lines as those of the proof of Theorem 4.

Remark 5. We cannot deduce Theorem 3.2 from Theorem 11.1 in Cârjă-Necula-Vrabie [5] because the multi-function G is only strongly-weakly u.s.c., so, in this case, $\mathcal{A} + \mathcal{F}$ it cannot be locally of compact type.

5 An example

Let $\Omega \subseteq \mathbf{R}^n$, $n = 1, 2, \dots$ be a bounded domain with C^2 boundary Γ , let $\delta_1 \geq 0$, $\delta_2 > 0$, $p > 0$, $q > 0$, let $f : \mathbf{R} \times \mathbf{R} \rightarrow \mathbf{R}_+$, $g_i : \mathbf{R} \times \mathbf{R} \rightarrow \mathbf{R}_-$ for $i = 1, 2$ be given functions and let us consider the following general semilinear predator-pray system

$$\begin{cases} u_t = \delta_1 \Delta u - pu + f(u, v) & (t, x) \in Q_{\tau, T} \\ v_t = \delta_2 \Delta v + qv + [g_1(u, v), g_2(u, v)] & (t, x) \in Q_{\tau, T} \\ u(t, x) = v(t, x) = 0 & (t, x) \in \Sigma_{\tau, T}, \\ u(\tau, x) = \xi(x), \quad v(\tau, x) = \eta(x) & x \in \Omega, \end{cases} \quad (21)$$

where $0 \leq \tau < T \leq \infty$, $Q_{\tau, T} = (\tau, T) \times \Omega$, $\Sigma_{\tau, T} = (\tau, T) \times \Gamma$, Δ is the usual Laplace operator, i.e. $\Delta u = \sum_{i=1}^n \frac{\partial^2 u}{\partial x_i^2}$ and $\xi, \eta \in L^2(\Omega)$. We assume that f is continuous function, g_1 is bounded and l.s.c. and g_2 is bounded and u.s.c. function on $\mathbf{R} \times \mathbf{R}$ and $g_1(u, v) \leq g_2(u, v)$ for each $(u, v) \in \mathbf{R} \times \mathbf{R}$. Let $\tilde{f} : \mathbf{R} \times \mathbf{R} \rightarrow \mathbf{R}_+$ and $\tilde{g} : \mathbf{R} \times \mathbf{R} \rightarrow \mathbf{R}_-$ be two continuous functions such that

$$\begin{cases} f(u, v) \leq \tilde{f}(u, v) \\ g_2(u, v) \geq \tilde{g}(u, v) \end{cases} \quad (22)$$

for each $(u, v) \in \mathbf{R} \times \mathbf{R}$. Let us consider also the comparison predator-pray system

$$\begin{cases} u_t = \delta_1 \Delta u - pu + \tilde{f}(u, v) & (t, x) \in Q_{0, \infty} \\ v_t = \delta_2 \Delta v + qv + \tilde{g}(u, v) & (t, x) \in Q_{0, \infty} \\ u(t, x) = v(t, x) = 0 & (t, x) \in \Sigma_{0, \infty}, \\ u(0, x) = u_0(x), \quad v(0, x) = v_0(x) & x \in \Omega, \end{cases} \quad (23)$$

where $u_0, v_0 \in L^2(\Omega)$, $u_0(x) \geq 0, v_0(x) \geq 0$ a.e. for $x \in \Omega$. Let $(\tilde{u}, \tilde{v}) : \mathbf{R}_+ \times \Omega \rightarrow \mathbf{R}_+ \times \mathbf{R}_+$ be a mild solution of (23).

Using the viability result, we are interested to show that, in the specific hypotheses, for each $(\xi, \eta) \in L^2(\Omega) \times L^2(\Omega)$, with

$$\begin{cases} 0 \leq \xi(x) \leq \tilde{u}(\tau, x) \\ \eta(x) \geq \tilde{v}(\tau, x) \end{cases} \quad (24)$$

a.e. for $x \in \Omega$, the system (21) has at least one solution $(u, v) : \mathbf{R}_+ \times \Omega \rightarrow \mathbf{R}_+ \times \mathbf{R}_+$, such that, for each $t \in [\tau, \infty)$, we have

$$\begin{cases} 0 \leq u(t, x) \leq \tilde{u}(t, x) \\ v(t, x) \geq \tilde{v}(t, x) \end{cases} \quad (25)$$

a.e. for $x \in \Omega$.

Let $\mathcal{K} \subseteq \mathbf{R} \times L^2(\Omega) \times L^2(\Omega)$ be defined by

$$\mathcal{K} = \{(t, u, v) \in \mathbf{R}_+ \times L^2(\Omega) \times L^2(\Omega); (u, v) \text{ satisfies (27) below}\} \quad (26)$$

$$\begin{cases} 0 \leq u(x) \leq \tilde{u}(t, x) \\ v(x) \geq \tilde{v}(t, x) \end{cases} \quad (27)$$

a.e. for $x \in \Omega$.

Theorem 7. *Let $\Omega \subseteq \mathbf{R}^n$, $n = 1, 2, \dots$, be a bounded domain with C^2 boundary Γ , $\delta_1 \geq 0$, $\delta_2 > 0$ and let $f : \mathbf{R} \times \mathbf{R} \rightarrow \mathbf{R}_+$ be continuous on $\mathbf{R} \times \mathbf{R}$ and globally Lipschitz with respect to its first argument, $g_1 : \mathbf{R} \times \mathbf{R} \rightarrow \mathbf{R}_-$ be bounded and l.s.c., $g_2 : \mathbf{R} \times \mathbf{R} \rightarrow \mathbf{R}_-$ be bounded and u.s.c. such that $g_1(u, v) \leq g_2(u, v)$ for each $(u, v) \in \mathbf{R} \times \mathbf{R}$. Let $\tilde{f} : \mathbf{R} \times \mathbf{R} \rightarrow \mathbf{R}_+$, $\tilde{g} : \mathbf{R} \times \mathbf{R} \rightarrow \mathbf{R}_-$ be continuous such that (22) are satisfied. Assume that, for each $(u_0, v_0) \in \mathbf{R} \times \mathbf{R}$, $u \mapsto \tilde{f}(u, v_0)$ and $v \mapsto \tilde{g}(u_0, v)$ are nondecreasing, $u \mapsto \tilde{g}(u, v_0)$ and $v \mapsto \tilde{f}(u_0, v)$ are nonincreasing and there exist the constants $c_i \geq 0$, $i = 1, \dots, 5$ such that $|\tilde{f}(u, v)| \leq c_1|u| + c_2$, and $|\tilde{g}(u, v)| \leq c_3|u| + c_4|v| + c_5$ for each $(u, v) \in \mathbf{R} \times \mathbf{R}$. Let $(u_0, v_0) \in L^2(\Omega) \times L^2(\Omega)$ with $u_0(x) \geq 0$ and $v_0(x) \geq 0$ a.e. for $x \in \Omega$ and let $(\tilde{u}, \tilde{v}) : \mathbf{R}_+ \rightarrow L^2(\Omega) \times L^2(\Omega)$ be a global mild solution of (23) with $\tilde{u}(t, x) \geq 0$ for each $t \geq 0$ and a.e. for $x \in \Omega$. Let \mathcal{K} be defined by (26). Then, for each $(\tau, \xi, \eta) \in \mathcal{K}$, the problem (21) has at least one global mild solution $(u, v) : [\tau, \infty) \rightarrow L^2(\Omega) \times L^2(\Omega)$ satisfying $(t, u(t), v(t)) \in \mathcal{K}$, for each $t \in [\tau, \infty)$.*

Proof. Let us denote by $X = L^2(\Omega)$. We rewrite (21) and (23) as an evolution systems in $X \times X$. Let us define $A : D(A) \subseteq X \rightarrow X$ and $B : D(B) \subseteq X \rightarrow X$ by

$$D(A) = H_0^1(\Omega) \cap H^2(\Omega) \quad \text{and} \quad Au = \delta_1 \Delta u - pu \quad \text{for } u \in D(A)$$

and respectively by

$$D(B) = H_0^1(\Omega) \cap H^2(\Omega) \quad \text{and} \quad Bv = \delta_2 \Delta v + qv \quad \text{for } v \in D(B).$$

Let us define $F : X \times X \rightarrow X$ and $G : X \times X \rightsquigarrow X$ by

$$F(u, v)(x) = f(u(x), v(x)) \text{ for each } (u, v) \in X \times X \text{ and a.e. for } x \in \Omega$$

and respectively by

$$G(u, v) = \{g \in L^2(\Omega); g_1(u(x), v(x)) \leq g(x) \leq g_2(u(x), v(x)) \text{ a.e. for } x \in \Omega\}$$

for each $(u, v) \in X \times X$. Let us observe that F is well-defined, continuous on $X \times X$ and is globally Lipschitz with respect to its first argument. Since g_1 is l.s.c., g_2 is u.s.c. and both are bounded, we conclude that G is strongly-weakly u.s.c. with nonempty, convex and weakly compact values. Let us define $\tilde{F} : X \times X \rightarrow X$ and $\tilde{G} : X \times X \rightarrow X$ by

$$\tilde{F}(u, v)(x) = \tilde{f}(u(x), v(x)) \quad \text{and} \quad \tilde{G}(u, v)(x) = \tilde{g}(u(x), v(x))$$

for each $(u, v) \in X \times X$ and a.e. for $x \in \Omega$. Since \tilde{f} and \tilde{g} are continuous and have sublinear growth, \tilde{F} and \tilde{G} are well-defined, continuous and have sublinear growth. With the notations above, the problem (21) can be rewritten as the abstract system

$$\begin{cases} u'(t) = Au(t) + F(u(t), v(t)) \\ v'(t) \in Bv(t) + G(u(t), v(t)) \\ u(\tau) = \xi, v(\tau) = \eta, \end{cases} \quad (28)$$

while (23) takes the abstract form

$$\begin{cases} u'(t) = Au(t) + \tilde{F}(u(t), v(t)) \\ v'(t) = Bv(t) + \tilde{G}(u(t), v(t)) \\ u(0) = u_0, v(0) = v_0. \end{cases} \quad (29)$$

We have to show first that \mathcal{K} is viable with respect to $(A + F, B + G)$ and second that every mild solution $(u, v) : [\tau, T) \rightarrow X \times X$, satisfying $(t, u(t), v(t)) \in \mathcal{K}$ for each $t \in [\tau, T)$, can be extended to a global one obeying the very same constraints. Let $\tilde{\mathcal{K}} \subseteq \mathbf{R}_+ \times L^2(\Omega) \times L^2(\Omega)$ be defined by

$$\tilde{\mathcal{K}} = \{(t, u, v) \in \mathbf{R}_+ \times L^2(\Omega) \times L^2(\Omega); (u, v) \text{ satisfy (31) below}\}. \quad (30)$$

$$u(x) \leq \tilde{u}(t, x), \quad v(x) \geq \tilde{v}(t, x) \quad (31)$$

a.e. for $x \in \Omega$. To prove that \mathcal{K} is viable with respect to $(A + F, B + G)$ it suffices to show that $\tilde{\mathcal{K}}$ is viable with respect to $(A + F, B + G)$. This is

a direct consequence of the maximum principle for parabolic equations—see Theorem 1.7.5. in Cârjă-Necula-Vrabie [6]— combined with the fact that F and \tilde{u} are nonnegative. In view of Theorem 6, to show that $\tilde{\mathcal{K}}$ is viable with respect to $(A + F, B + G)$, we have merely to check the tangency condition

$$((\tau + h, S_A(h)\xi + hF(\xi, \eta), S_B(h)\eta + hG(\xi, \eta)) \in \mathcal{QTS}_{\tilde{\mathcal{K}}}^A(\tau, \xi, \eta) \quad (32)$$

for each $(\tau, \xi, \eta) \in \tilde{\mathcal{K}}$, where $\{S_A(t) : X \rightarrow X, t \geq 0\}$ is the C_0 -semigroup generated by A and $\{S_B(t) : X \rightarrow X, t \geq 0\}$ is the compact C_0 -semigroups generated by B and $\mathcal{A} = (A, B)$.

Let $(\tau, \xi, \eta) \in \tilde{\mathcal{K}}$. To prove (32) it suffices that for each $h > 0$ there exist $(u_h, v_h) \in X \times X$ and $g_h \in G(\xi, \eta)$ with $(\tau + h, u_h, v_h) \in \tilde{\mathcal{K}}$ and

$$\begin{cases} \liminf_{h \downarrow 0} \frac{1}{h} \|S_A(h)\xi + hF(\xi, \eta) - u_h\| = 0 \\ \liminf_{h \downarrow 0} \frac{1}{h} \|S_B(h)\eta + hg_h - v_h\| = 0. \end{cases} \quad (33)$$

Let us define $g_h(x) = g_2(\xi(x), \eta(x))$ a.e. for $x \in \Omega$ and u_h and v_h by

$$\begin{aligned} u_h &= S_A(h)\xi + \int_{\tau}^{\tau+h} S_A(\tau + h - s)F(\xi, \eta) ds \\ &+ \int_{\tau}^{\tau+h} S_A(\tau + h - s)[\tilde{F}(\tilde{u}(s), \tilde{v}(s)) - \tilde{F}(\tilde{u}(\tau), \tilde{v}(\tau))] ds \end{aligned}$$

and respectively by

$$\begin{aligned} v_h &= S_B(h)\eta + \int_{\tau}^{\tau+h} S_B(\tau + h - s)g_h ds \\ &+ \int_{\tau}^{\tau+h} S_B(\tau + h - s)[\tilde{G}(\tilde{u}(s), \tilde{v}(s)) - \tilde{G}(\tilde{u}(\tau), \tilde{v}(\tau))] ds. \end{aligned}$$

Now let us observe that, inasmuch as $\xi \leq \tilde{u}(\tau)$ and $\eta \geq \tilde{v}(\tau)$ a.e. on Ω , we have both

$$S_A(h)\xi \leq S_A(h)\tilde{u}(\tau) \quad \text{and} \quad S_B(h)\eta \geq S_B(h)\tilde{v}(\tau).$$

See Theorem 1.7.5 in Cârjă-Necula-Vrabie [6]. Recalling that $f \leq \tilde{f}$ and taking into account of the monotonicity properties of \tilde{f} , we get

$$F(\xi, \eta) \leq \tilde{F}(\xi, \eta) \leq \tilde{F}(\tilde{u}(\tau), \tilde{v}(\tau)).$$

Using the fact that $g_2 \geq \tilde{g}$ and the monotonicity properties of \tilde{g} , we deduce

$$g_h \geq \tilde{G}(\xi, \eta) \geq \tilde{G}(\tilde{u}(\tau), \tilde{v}(\tau)).$$

So, we get both $u_h \leq \tilde{u}(\tau+h)$ and $v_h \geq \tilde{v}(\tau+h)$ and thus $(\tau+h, u_h, v_h) \in \tilde{\mathcal{K}}$. On the other hand

$$\begin{aligned} \|S_A(h)\xi + hF(\xi, \eta) - u_h\| &\leq \int_{\tau}^{\tau+h} \|S_A(\tau+h-s)F(\xi, \eta) - F(\xi, \eta)\| ds \\ &\quad + Me^{ah} \int_{\tau}^{\tau+h} \|\tilde{F}(\tilde{u}(s), \tilde{v}(s)) - \tilde{F}(\tilde{u}(\tau), \tilde{v}(\tau))\| ds, \end{aligned}$$

where $M \geq 1$ and $a > 0$ are the growth constants of the C_0 -semigroups $\{S_A(t) : X \rightarrow X, t \geq 0\}$ and $\{S_B(t) : X \rightarrow X, t \geq 0\}$. Since \tilde{F} , \tilde{u} and \tilde{v} are continuous we conclude that the first equality in (33) holds. Similarly, we have

$$\begin{aligned} \|S_B(h)\eta + hg_h - v_h\| &\leq \int_{\tau}^{\tau+h} \|S_B(\tau+h-s)g_h - g_h\| ds \\ &\quad + Me^{ah} \int_{\tau}^{\tau+h} \|\tilde{G}(\tilde{u}(s), \tilde{v}(s)) - \tilde{G}(\tilde{u}(\tau), \tilde{v}(\tau))\| ds, \end{aligned}$$

and we get the second equality from (33). This completes the proof of the viability of $\tilde{\mathcal{K}}$ and consequently the viability of \mathcal{K} . Let us observe that \mathcal{K} satisfies the next property: for each sequence $((t_n, \xi_n, \eta_n))_n$ in \mathcal{K} with $\lim_n(t_n, \xi_n, \eta_n) = (t, \xi, \eta)$ and $t < T_{\mathcal{K}}$, where $T_{\mathcal{K}}$ is given by (34) below, it follows that $(t, \xi, \eta) \in \mathcal{K}$.

$$T_{\mathcal{K}} = \sup\{t \in \mathbf{R}; \text{ there exist } (\xi, \eta) \in X \times X, \text{ with } (t, \xi, \eta) \in \mathcal{K}\}. \quad (34)$$

Then it follows that each mild solution $(u, v) : [\tau, T] \rightarrow X \times X$ of (21) satisfying $(t, u(t), v(t)) \in \mathcal{K}$ for each $t \in [\tau, T]$ can be continued up to a global one $(u^*, v^*) : [\tau, T_{\mathcal{K}}] \rightarrow X \times X$ satisfying the very same condition on $[\tau, T_{\mathcal{K}}]$. Since (\tilde{u}, \tilde{v}) is defined on \mathbf{R}_+ and $(t, \tilde{u}(t), \tilde{v}(t)) \in \mathcal{K}$ for each $t \in [0, \infty)$, we conclude that $T_{\mathcal{K}} = \infty$ and this completes the proof.

References

- [1] M. Burlică. Viability for semi-multi-valued reaction-diffusion systems. In T.E. Simos, G. Psihoyios, Ch. Tsitouras(eds.) *Numerical Analysis and Applied Mathematics, International Conference, AIP*. Kos, Greece, 2008.

- [2] M. Burlică, D. Roşu. A Viability Result for Semilinear Reaction-Diffusion Systems (I). In O. Cârjă, I.I. Vrabie, (eds.) *Proceedings of the International Conference on Applied Analysis and Differential Equations.*, 4-9 September, Iaşi, România, (2006), 31-44.
- [3] M. Burlică, D. Roşu. A Viability Results for Semilinear Reaction-Diffusion Systems (II). *An. Ştiinţ. Univ. "Al. I. Cuza" Iaşi, Sect. Ia, Matematică.* TOM LIV, f2 (2008), 361-382.
- [4] O. Cârjă. *Some Methods of Nonlinear Functionals Analysis.* Matrix Rom, Bucureşti, 2003 (Romanian).
- [5] O.Cârjă, M. Necula, I.I.Vrabie. Necessary and Sufficient Conditions for Viability for Semilinear Differential Inclusions. *Trans. Amer. Math. Soc.* 361, No. 1 (2009), 343-390.
- [6] O.Cârjă, M. Necula, I.I.Vrabie. *Viability, Invariance and Applications.* North-Holland Mathematics Studies, 207, Elsevier, 2007.
- [7] O.Cârjă, M. Necula, I.I.Vrabie. Necessary and sufficient conditions for viability for nonlinear evolution inclusions. *Set Valued Analysis.* 16, 2008, 701-731.
- [8] M. Necula, I.I.Vrabie. A viability result for a class of fully nonlinear reaction-diffusion systems. *Nonlinear Anal. Theor. Math. Appl.* 69, 2008, 1732-1743.
- [9] I.I. Vrabie. *C_0 -Semigroups and Applications.* North-Holland Mathematics Studies, 191, 2003.